CANnon: Stealthy Remote Shutdown Attacks via Automotive MCUs Sekar Kulandaivel, Automotive Security PhD Candidate

Motivation

Against evolving threat landscape

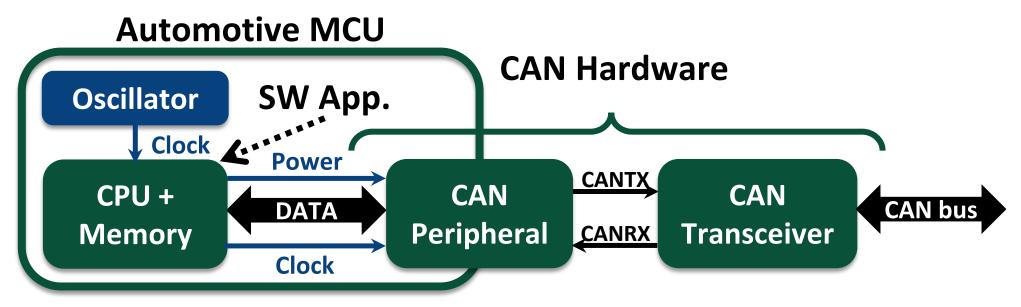
- Message authentication
- Intrusion detection systems
- Secure hardware solutions

Limitation of current attacks

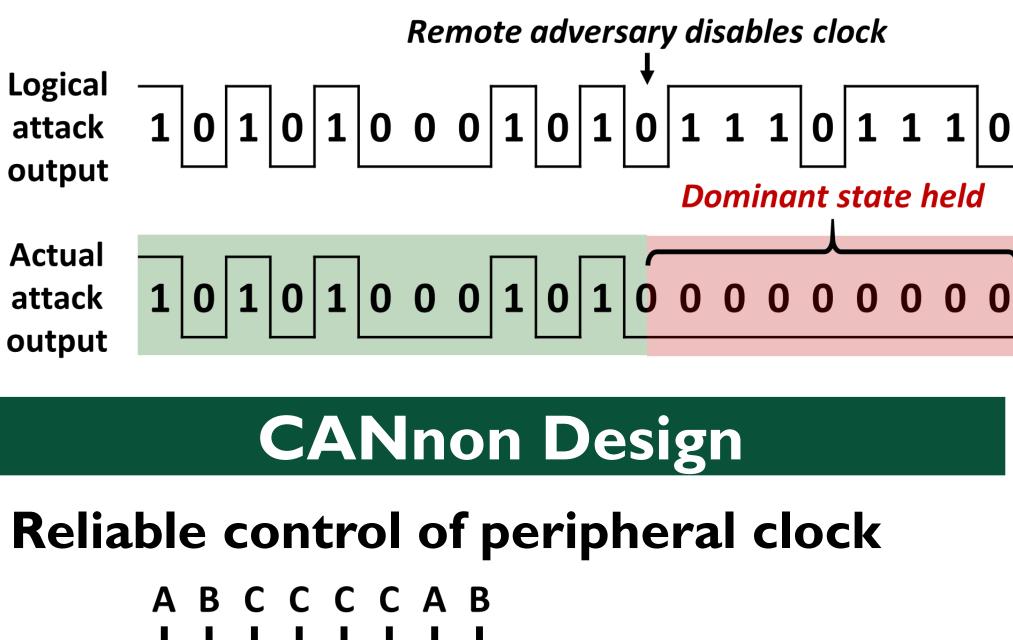
Existing attacks cannot simultaneously be:

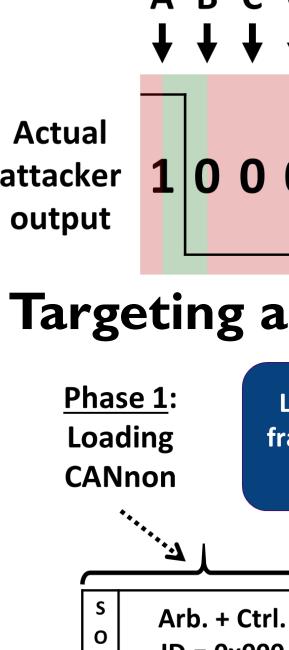
- <u>Remote</u> (software-based attack)
- Stealthy (against modern defenses)
- <u>Reliable</u> (practical in real scenario) 3.

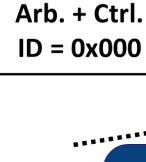
Modern ECU design with peripherals



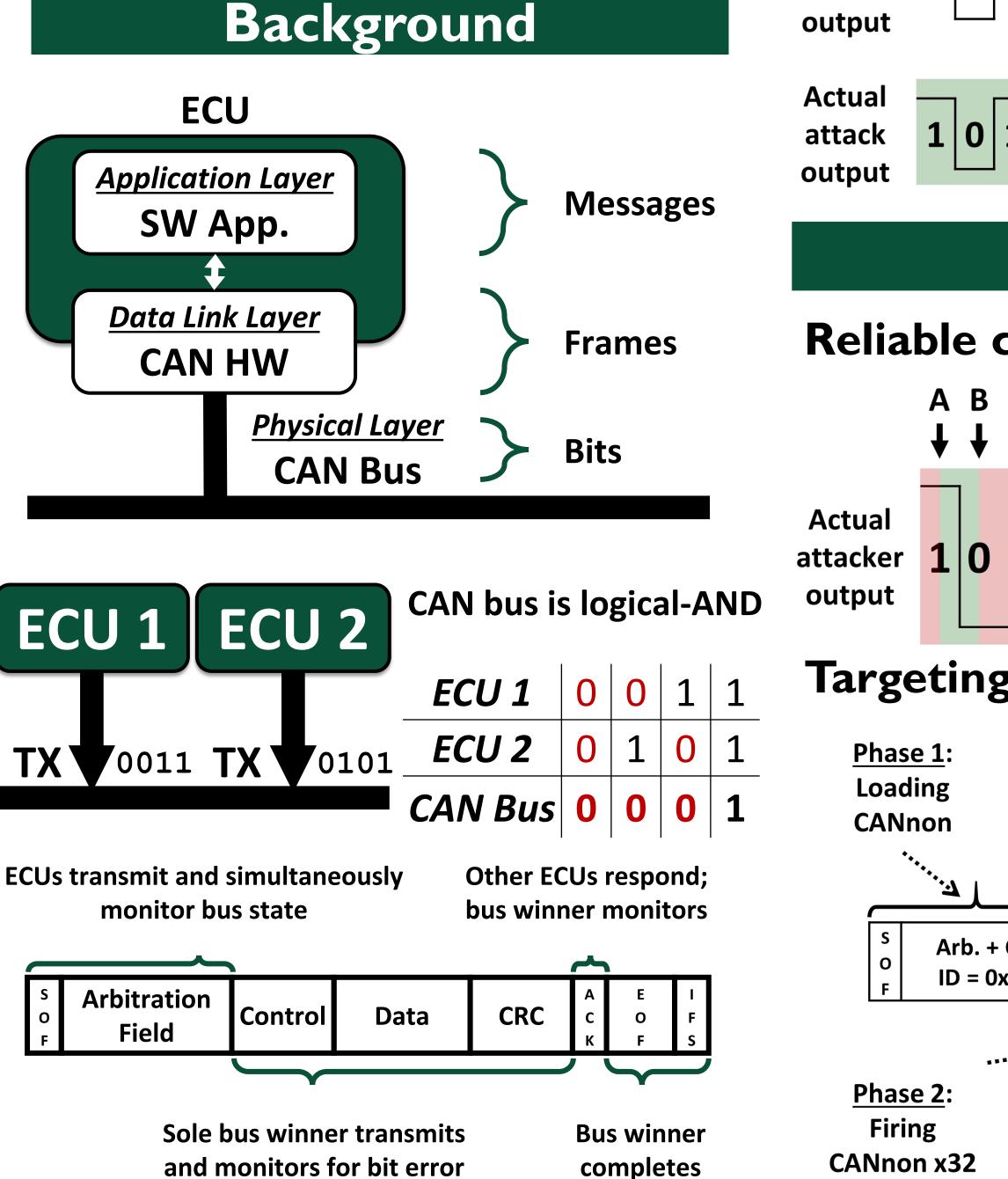
Clock control is now possible





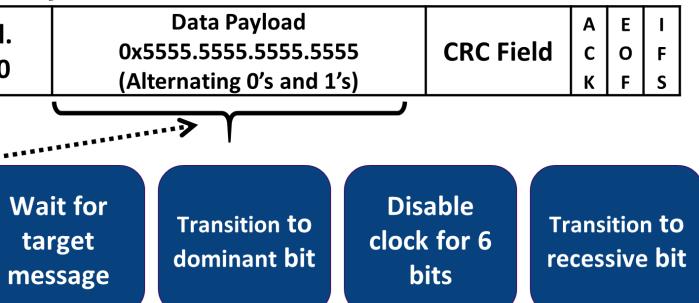


<u>Phase 2</u> :
Firing
CANnon x32



Attack Insight

\downarrow \downarrow \downarrow \downarrow \downarrow **ISR will either: Timer ISR** A. Enable clock Interrupts 0000001 B. Disable clock every CAN C. Do nothing bit time Targeting and shutting down a victim Load attack Transmit arb. + Wait for IFS to frame into TX ctrl. field and get bus access buffer wait Data Payload AEI **CRC** Field C O F 0x5555.5555.5555.5555 K F S (Alternating 0's and 1's) ••••••



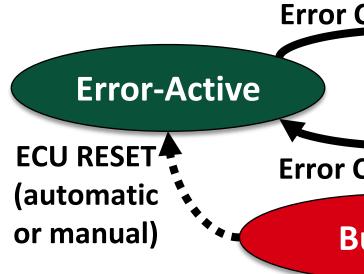
CANnon attack alternatives

- Firing with SOF bit
- Firing with ACKs

Practical challenges

- Period deviation in victim frames

Attacks on two real vehicles



- Powertrain ECU of `17 Ford Focus

Countermeasures

Prevention

- Forced clear of transmit buffers
- Removal of clock gating for CAN

Detection

- Detecting bit-wise voltage spikes
- On-chip power analysis





Key Results

- Guarantee victim frame time by forcing ordered queuing of frames Interruptions by higher-priority frames Use CANvas network mapper to identify highest-priority frame

Error Count > 127 **Error-Passive** Error Count ≤ 127 Error Count > 255 **Bus-Off** Shutdown in 2ms but auto-recovers Power steering ECU of `09 Toyota Prius Permanent shutdown in 700ms

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