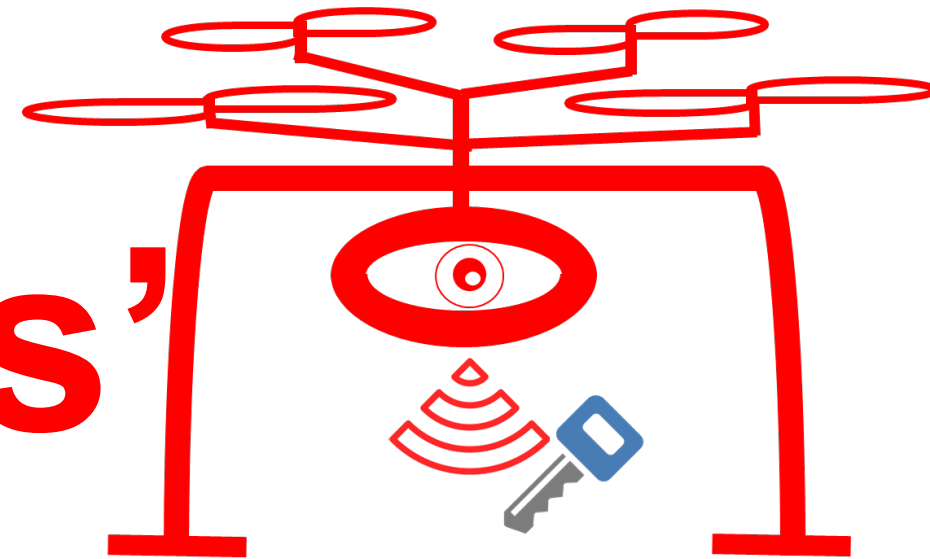




**CBG**

Cyber@ Ben-Gurion University  
Telekom Innovation Labs

# Drones' Cryptanalysis



**Ben Nassi**

**S** Prof. Adi Shamir

Raz Ben-Netanel

Prof. Yuval Elovici



IEEE  
COMPUTER  
SOCIETY

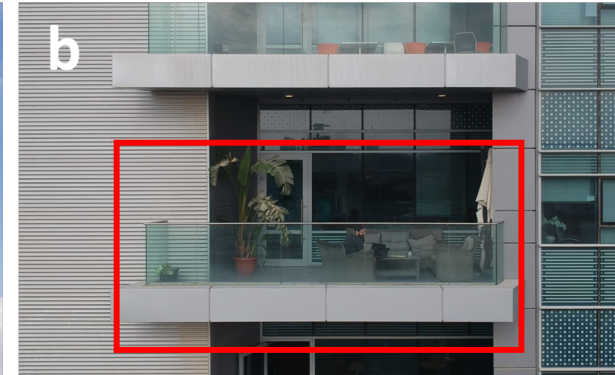


# Agenda

- 1) **Motivation**
- 2) **Detection Scheme**
- 3) **Wi-Fi FPV and Video Compression**
- 4) **FPV Channel Classification**
- 5) **Detecting Whether an FPV Channel is Being Used to Spy on a Victim**
- 6) **Locating a Spying Drone in Space**
- 7) **Hiding the Flicker from the Drone's Operator**
- 8) **Evaluation in Real Scenarios**

# Research Question

In an "Open Skies" era in which drones can fly between us, a new challenge arises: how can we determine whether a drone that is passing near a house is being used by its operator for a **legitimate purpose** (e.g., delivering pizza) or an **illegitimate purpose** (e.g., spying on an organization)?



# Drones Create a New Threat to Privacy

Not in my backyard! Woman throws stones before using a GUN to get rid of nosy neighbour's drone

**Mail**Online

Kentucky Man Arrested After Shooting Down Neighbor's Drone

 NBC NEWS

Eyes In The Sky: The Public Has Privacy Concerns About Drones

**Forbes**

Spouses are using DRONES to catch their cheating partners

**Mail**Online

Drone complaints soar as concerns grow over snooping

**theguardian**

Are Drones Spying on Miley Cyrus and Selena Gomez?

**People**

The drones among us: Reports of drone-related incidents are going up and up and up

**NATIONAL POST**



# Drone Adoption Rates Increase Around the World

- **Drone Adoption**

Businesses around the world have started to adopt drones for various purposes (e.g., deliveries).



- **“Open Skies” Policy**

Regulations are being changed, allowing drones to fly in populated areas (adopting an “Open Skies” Policy in cities).

JACK STEWART TRANSPORTATION 10.26.17 08:00 AM

## PRESIDENT TRUMP MOVES TO FILL AMERICA'S SKIES WITH DRONES

**FAA proposes relaxing drone laws,  
potentially allowing drone  
deliveries to begin**



Loz Blain | January 15th, 2019

# Geofencing Methods for Drone Detection



Radar



Camera



LiDAR



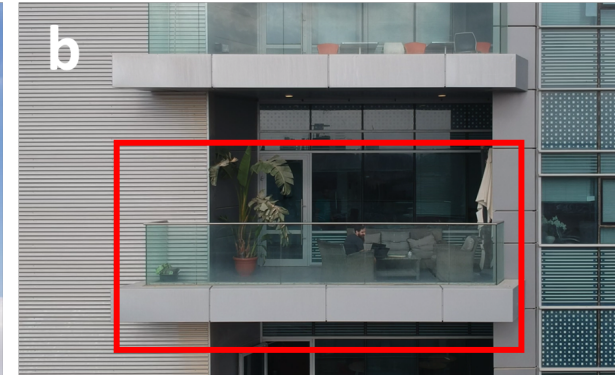
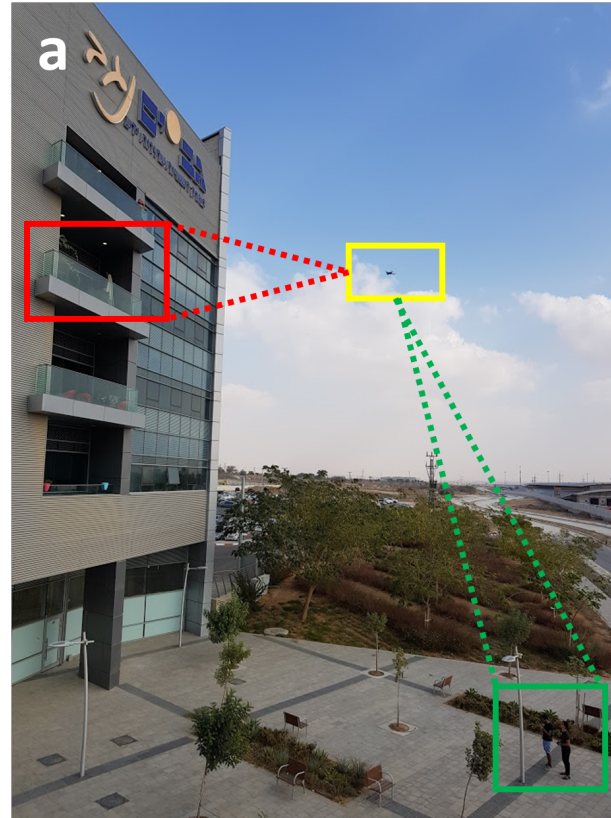
Microphone Array

**These methods are able to detect the presence of nearby drones.**

# Geofencing Methods for Drone Detection

## Do Geofencing methods effective at detecting a privacy invasion attack?

1. The presence of drones is **no longer restricted** in populated areas.
2. The difference between legitimate use of a drone and illegitimate use depends on the drone's **camera orientation** rather than on the drone's location.



**Geofencing methods are irrelevant for detecting a privacy invasion attack in the “Open Skies” era.**

# Objective

Main Objective: Detecting a privacy invasion attack.

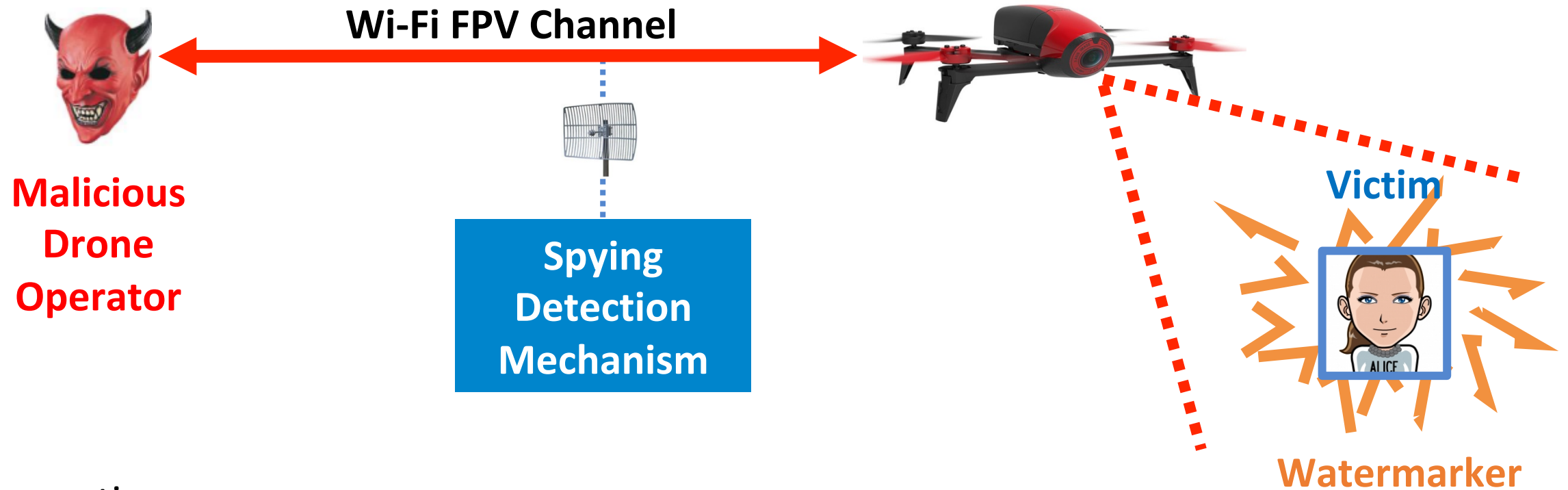
- ☐ Classifying a suspicious radio transmission as an FPV channel.
- ☐ Detecting an FPV channel's quality (FPS and resolution).
- ☐ Detecting whether an FPV channel is being used to spy on a victim (even if the victim is not static).
- ☐ Locating a spying drone in space.
- ☐ Detecting a privacy invasion attack without the awareness of the drone's operator.

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# Target Detection Scheme



## Assumptions:

- 1) The attacker is using a Wi-Fi FPV drone (located in a range of up to 5 KM from the victim).
- 2) The spy detection mechanism is connected to an RF scanner with a proper antenna for intercepting suspicious radio transmissions.

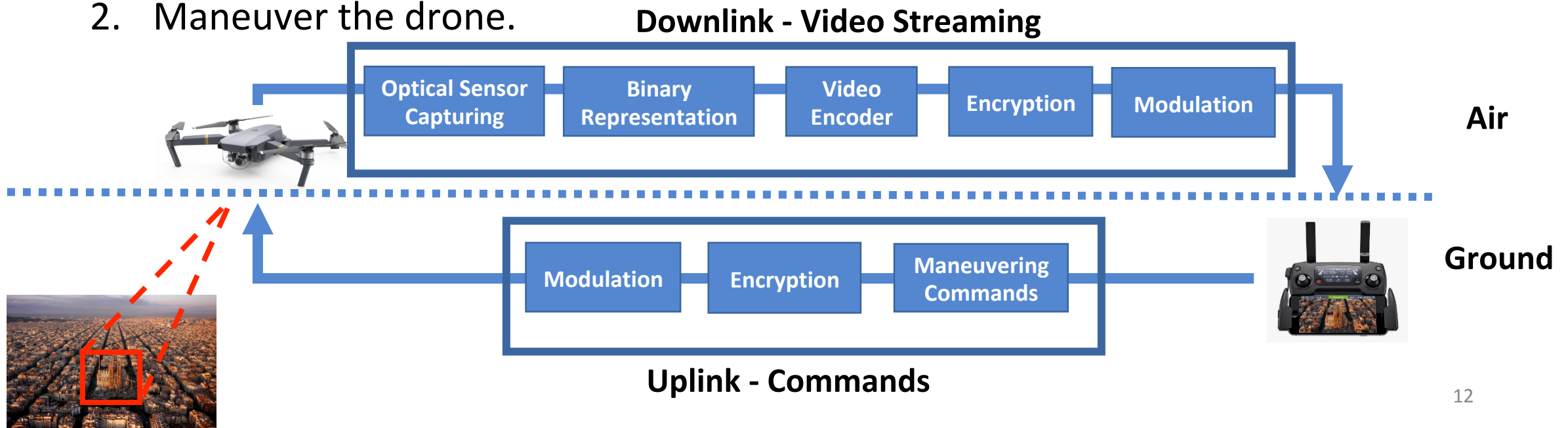
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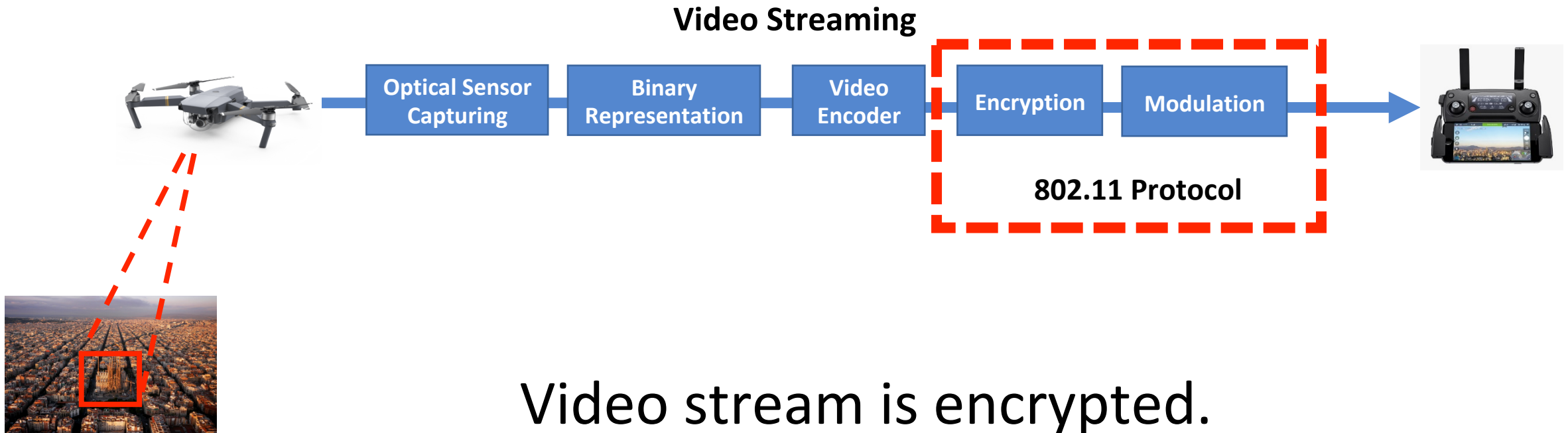
# Wi-Fi First-Person View Channel

**Wi-Fi First-Person View (FPV) Channel** - a communication channel based on Wi-Fi communication designed to:

1. Stream the video captured by the drone's video camera to the operator's controller.
2. Maneuver the drone.



# Downlink - Video Streaming Channel



Video stream is encrypted.  
Does encryption ensures confidentiality?

# Interception of an FPV Stream

Given a suspicious Wi-Fi transmission, we create an *intercepted bitrate signal*:

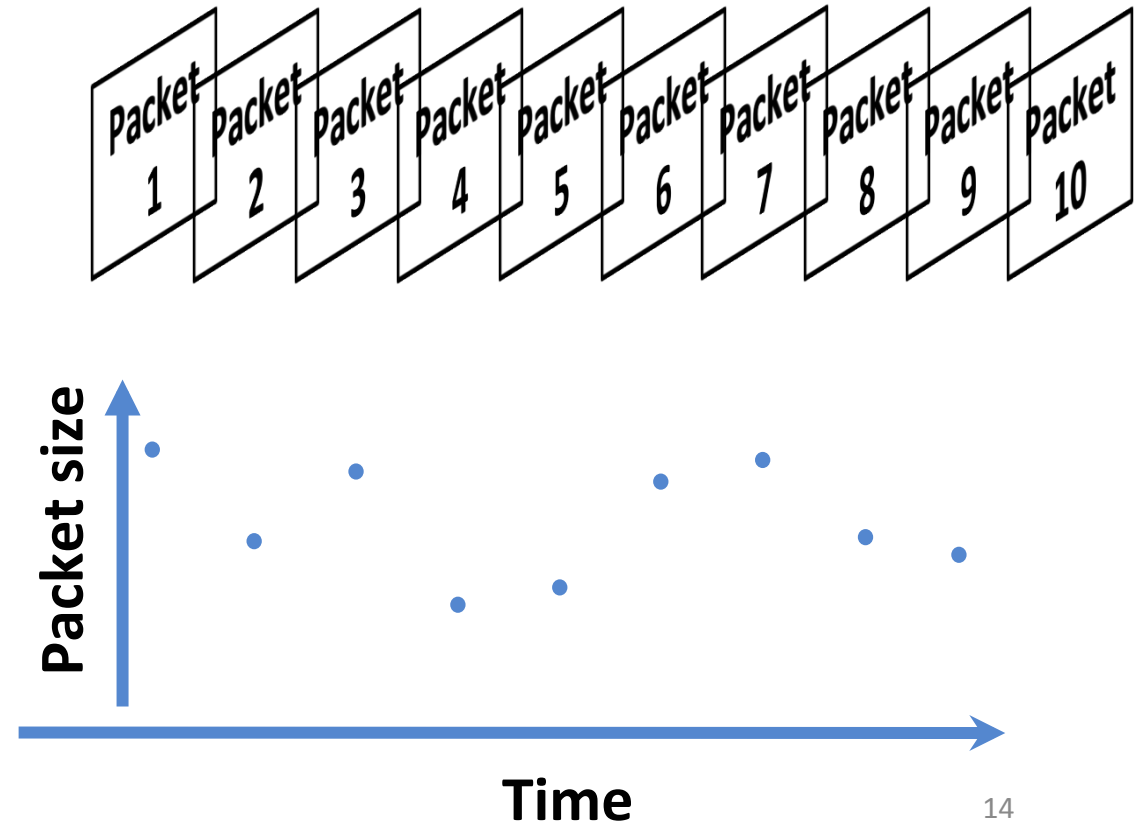
## 1) Sniffing Wi-Fi Packets

- Enabling NIC's monitoring mode (attack mode)
- Sniffing a network using **Airmon**

## 2) Extracting a time series signal from unencrypted metadata (2<sup>nd</sup> layer)

- Packet length (frame.len)
- Packet arrival time (frame.number)

## 3) Downsampling (by aggregating time series in a fixed window)





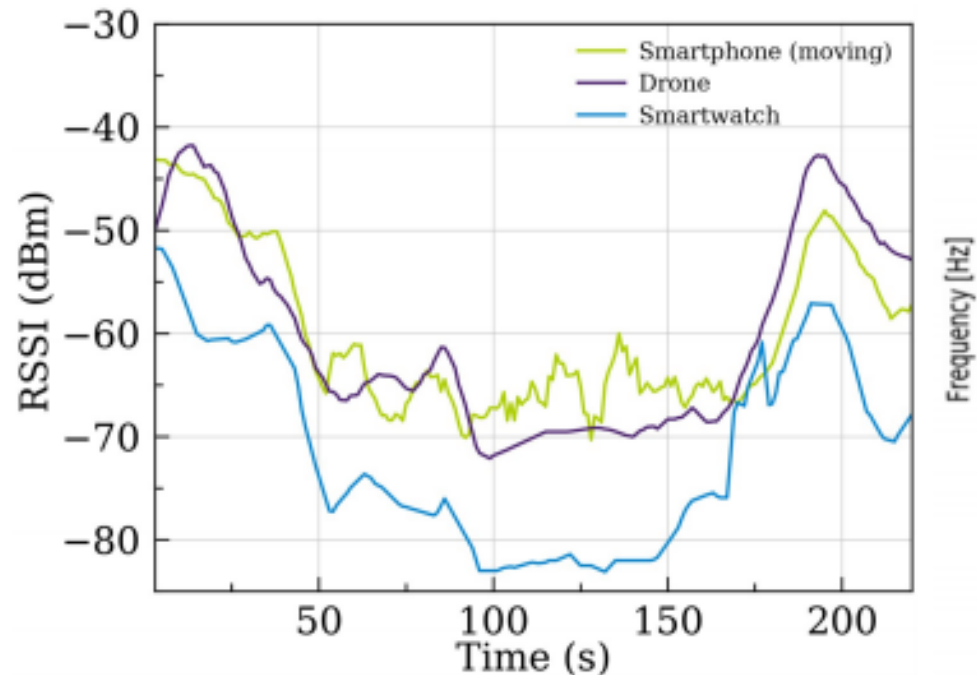
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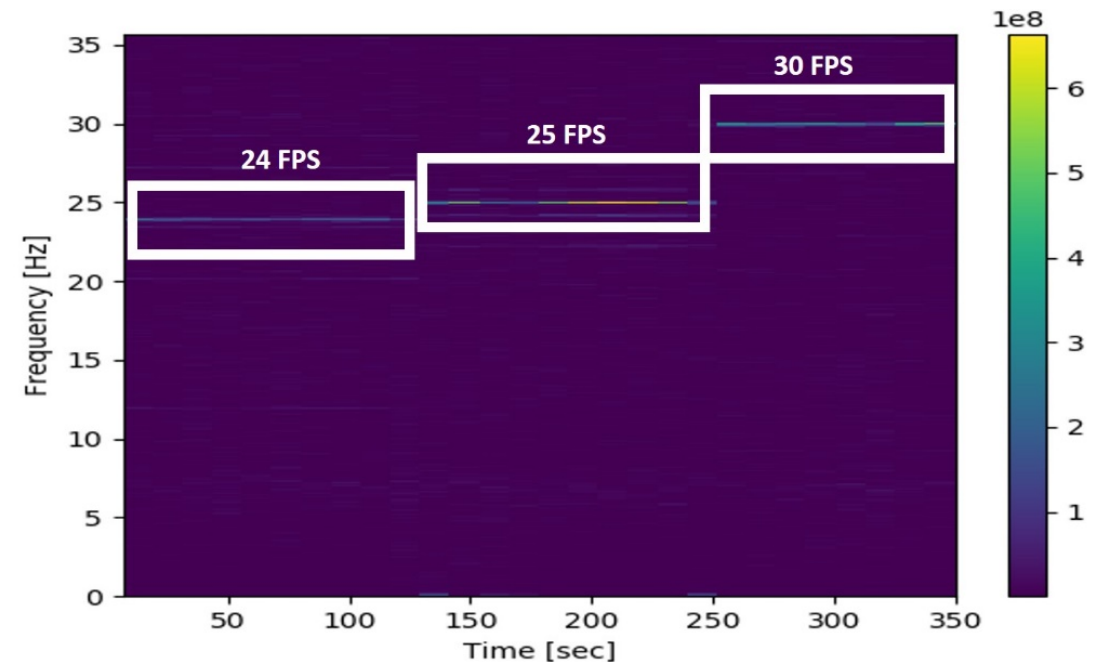
# Classifying a Suspicious Transmission as an FPV Channel

Key Observation: A drone is a **flying** camera.

## Moving Device Detection

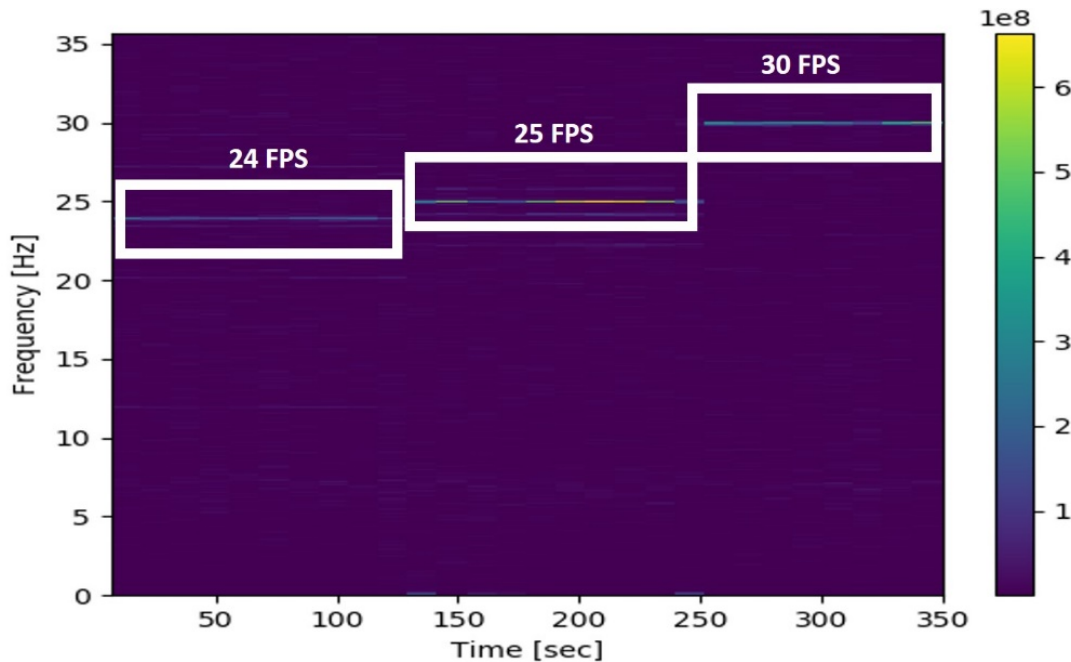


## Camera Detection



# Classifying a Suspicious Transmission as an FPV Channel

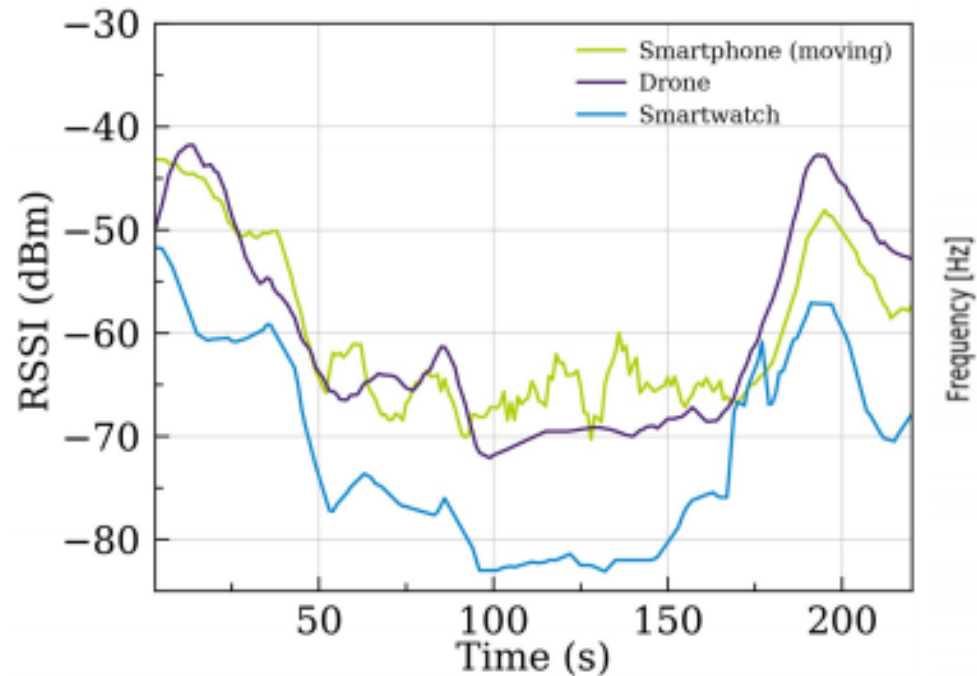
## Camera Detection



- 1) Analyzing the intercepted bitrate signal in the frequency domain.
- 2) Finding the frequency with the maximum magnitude.
- 3) Compare the frequency with the maximum magnitude to known frame per second rates of drones {24,25,30,60,96,120}.

# Classifying a Suspicious Transmission as an FPV Channel

## Moving Object Detection



- 1) Analyzing received signal strength indication measurements for a given device (MAC) over time.
- 2) Determining that a device is on the move according to measurement changes.

# Classifying a Suspicious Transmission as an FPV Channel

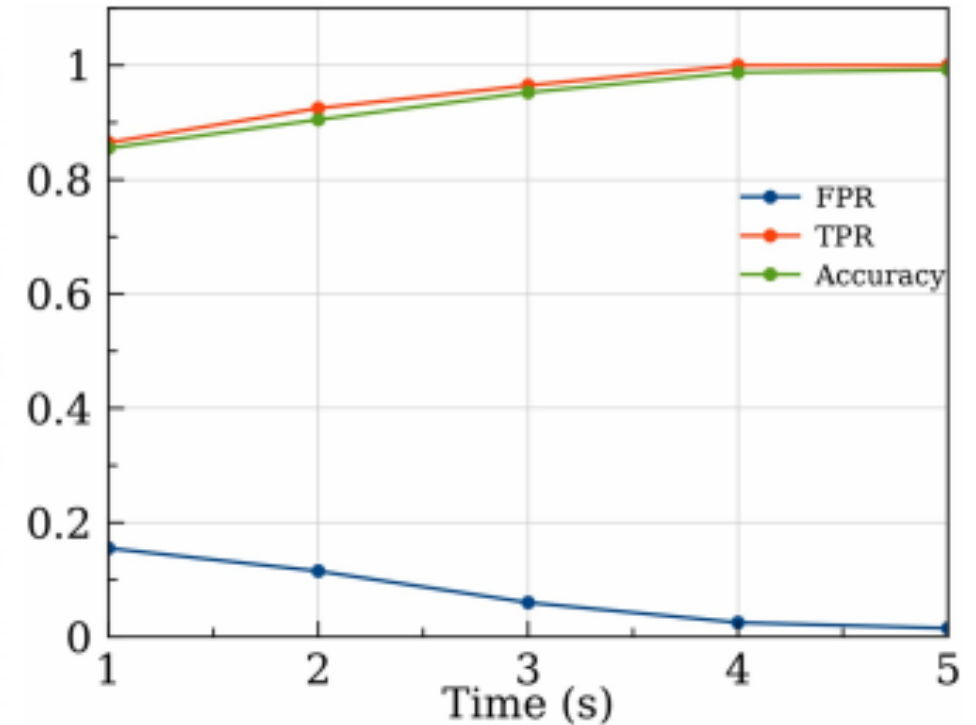
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**Algorithm 2** Classifying an FPV Channel

---

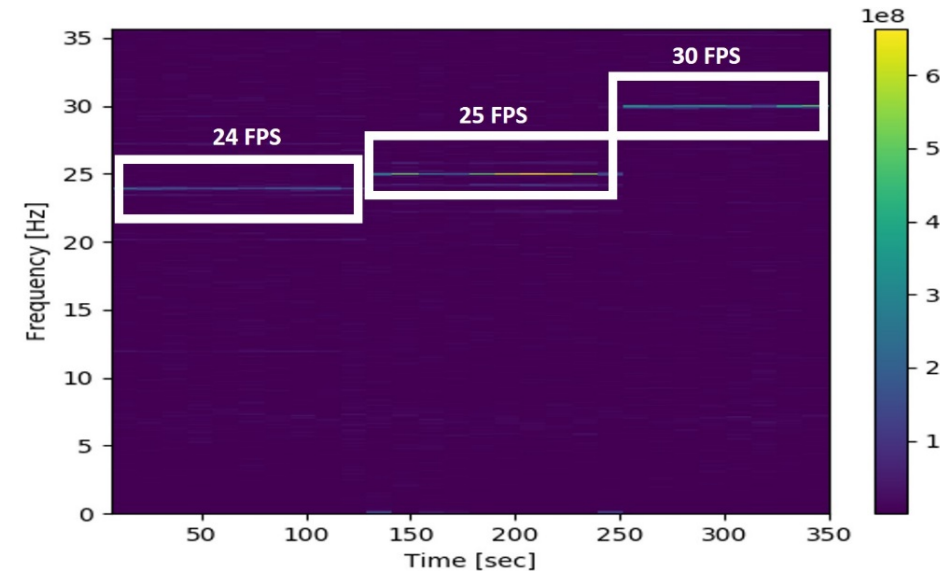
```
1: procedure ISFPVCHANNEL?(network,time)
2:   frequency = 70
3:   for (macAddress : network) do
4:     //Detecting Moving Objects
5:     if (isMovingObject(macAddress)) then
6:       bitrate[] = extractBitrateSignal(macAddress)
7:       fft [] = FFT(bitrateArray,frequency)
8:       index = frequencyWithStrongestMagnitude(fft)
9:       //Detecting video channel
10:      if (index==24 || index==25 || index==30) then
11:        return true
12:   return false
```

---



We can determine whether a suspicious radio transmission is an FPV channel within 4 seconds with accuracy of 99.9%.

# Detecting FPS and Resolution



FPV channel (bits per second) =

Drone to controller traffic (BPS) + Controller to drone traffic (BPS) =

**Video stream** + Metadata about the transmission + Maneuvering commands + Transmission's metadata =

**Video stream** +  $O(c)$  =

FPS x Resolution (Delta resolution) +  $O(c)$ .

$$\text{Resolution} = \frac{\text{FPV Channel (Bits Per Second)}}{\text{FPS}}$$

By applying FFT to the intercepted bitrate signal of an FPV channel we can detect the FPS and use it to calculate the resolution by analyzing the bitrate per second.

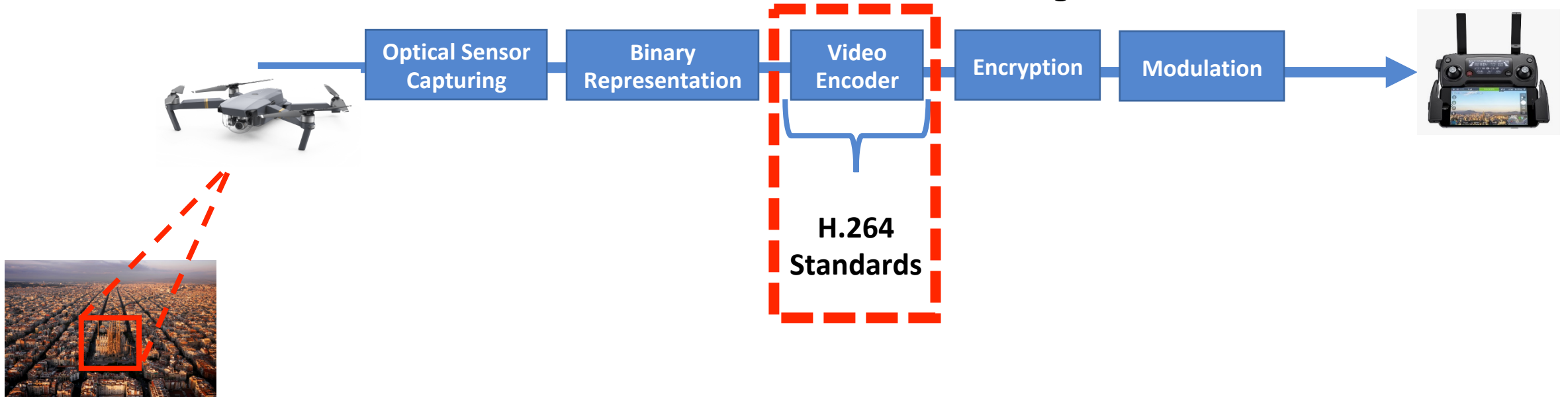
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# Video Compression Stage

## Downlink - Video Streaming

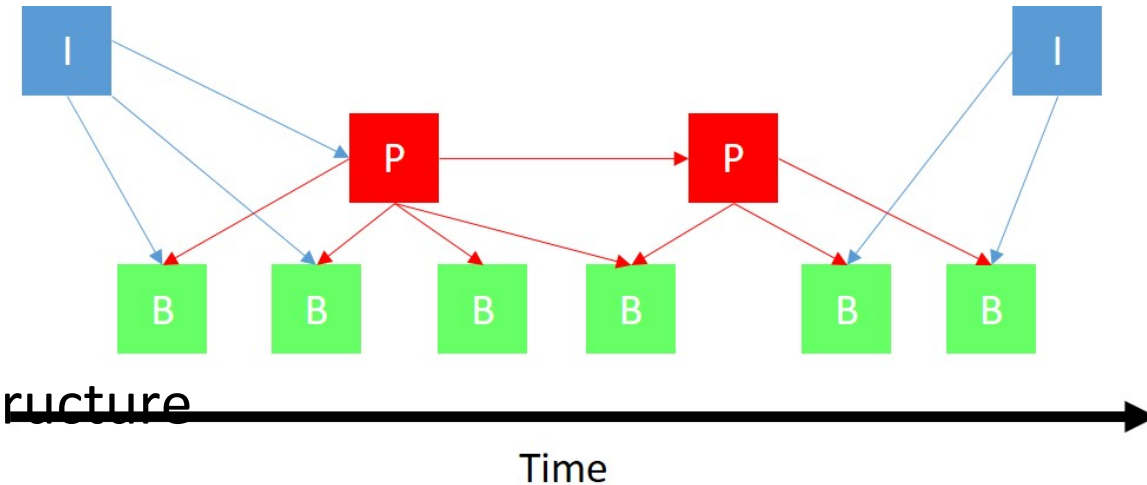


# H.264 Compression Standards

## Motion Compensation Algorithm

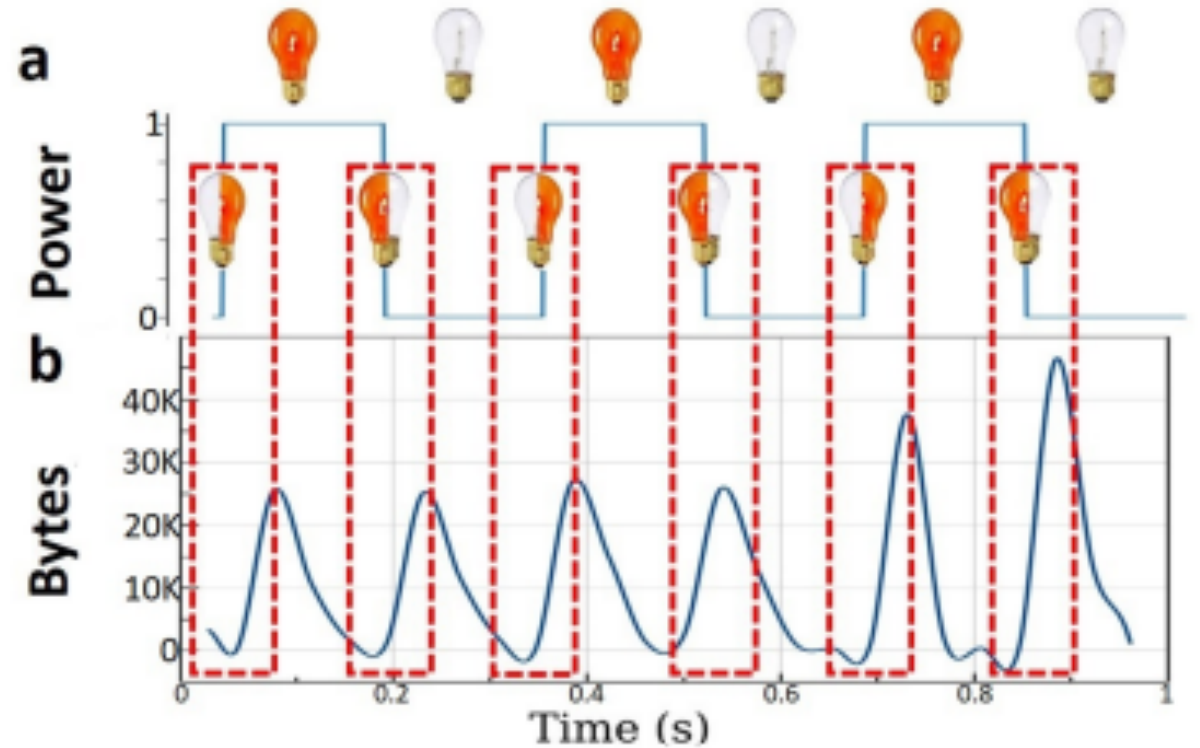
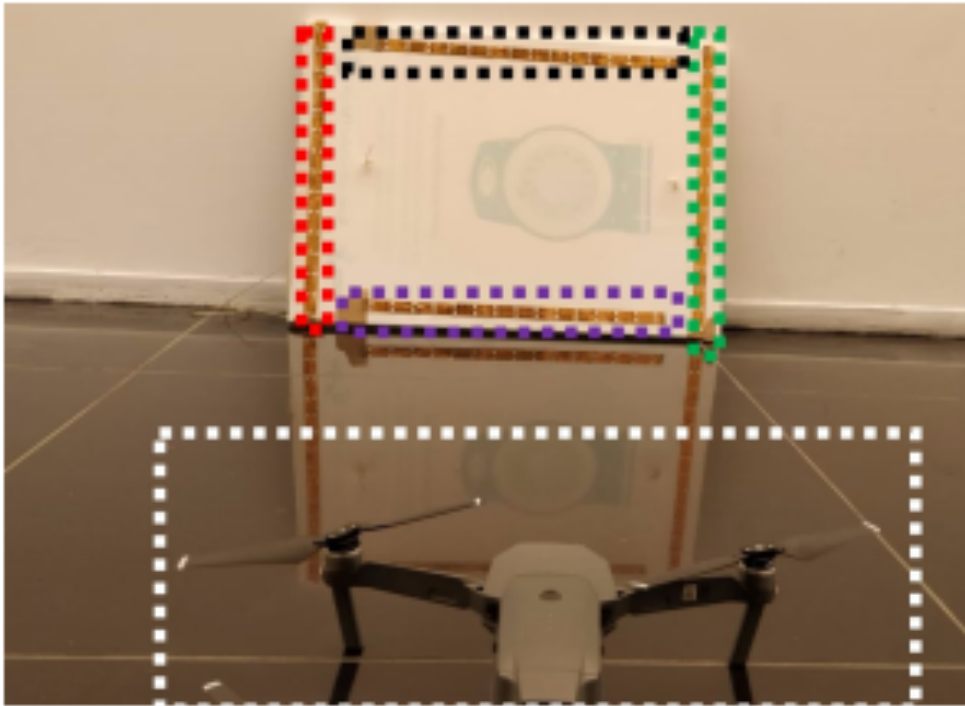
Instead of sending an entire frame, a frame is described as a delta (changes) from another frame, and this information is sent.

- Self-Contained Frames (I-Frames)
- Delta Frames (B-Frames and P-Frames)
- Data is sent in a GOP (group of picture) structure



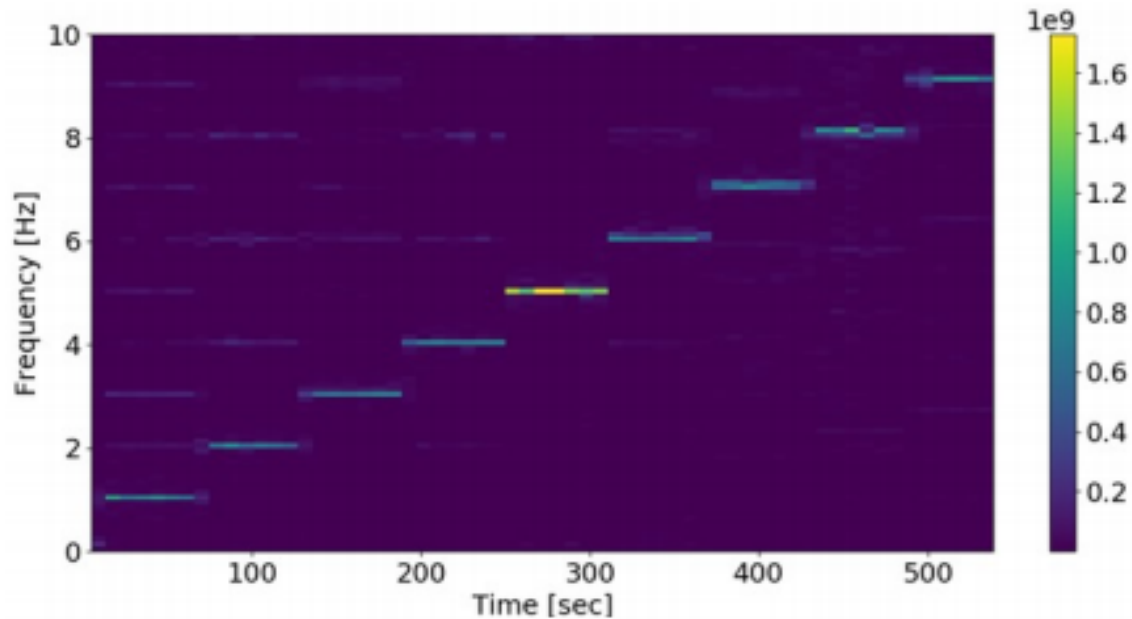
The result: If there are a lot of changes between two consecutive frames, a lot of data needs to be encoded, so the delta frames are much larger comparing to delta frames of two similar consecutive frames.

# Influence of Periodic Physical Stimulus on the Frequency Domain



Key Observation: a 3 Hz flickering LED created 6 bursts in the intercepted bitrate signal.

# Watermarking a Target Frequency



We can watermark each and every frequency of the intercepted bitrate signal using a flickering LED.

1. Detecting whether a specific POI is being streamed by a FPV channel by:
  - Launching a flicker with a frequency  $f$ .
  - Testing the change of magnitude of frequency  $2f$  of the intercepted bitrate signal in the frequency domain.
2. Frequency of maximum physical stimulus is limited to 12 Hz (because the minimal FPS rate of a commercial drone is 24 Hz)

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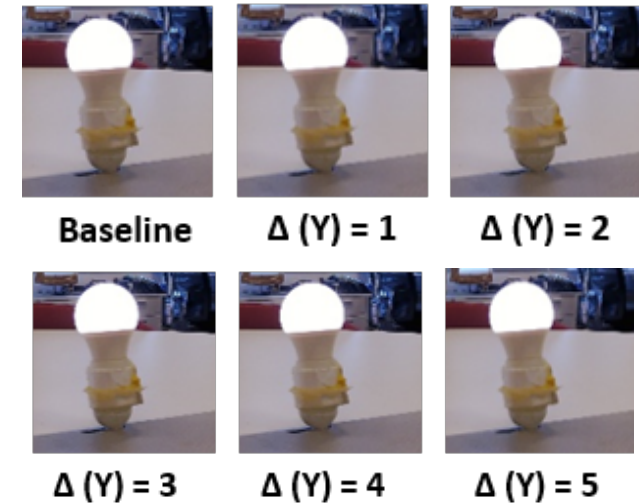
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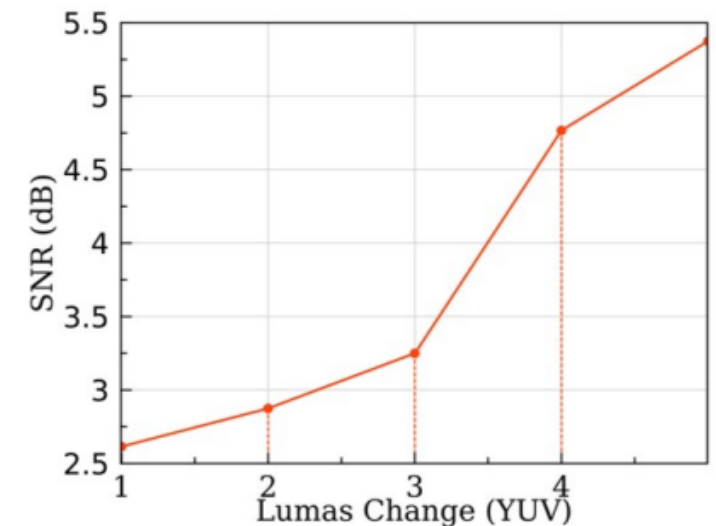
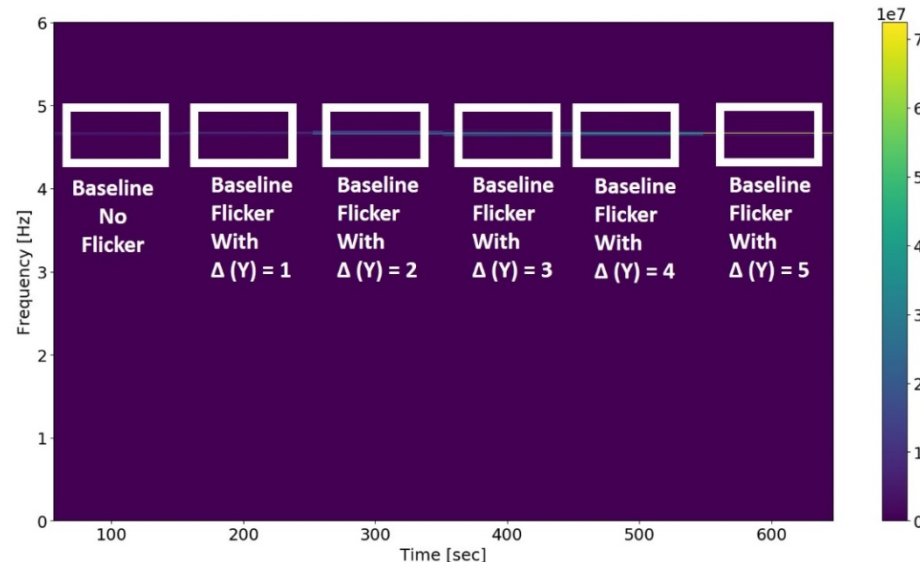
# Hiding the Physical Stimulus

Flickering between two similar hues

- a) Undetectable by direct observation ✓
- b) Undetectable by indirect observation ✓
- c) Watermark ✓



| Luma ( $\Delta$ ) | YUV        | RGB        |
|-------------------|------------|------------|
| Baseline          | 231,26,143 | 253,255,51 |
| 1                 | 230,26,143 | 252,254,50 |
| 2                 | 229,26,143 | 251,253,49 |
| 3                 | 228,26,143 | 250,252,48 |
| 4                 | 227,26,143 | 249,251,47 |
| 5                 | 226,26,143 | 248,250,46 |



# Optional Methods For Hiding the Physical Stimulus That Were Failed

Using an infrared projector

- a) Undetectable by direct observation ✓
- b) Undetectable via the controller ✗
- c) Watermark ✓



Applying the physical stimulus for a period of time that the human eye is unable to perceive (e.g., 10 milliseconds)

- a) Undetectable by direct observation ✓
- b) Undetectable via the controller ✗
- c) Watermark ✓

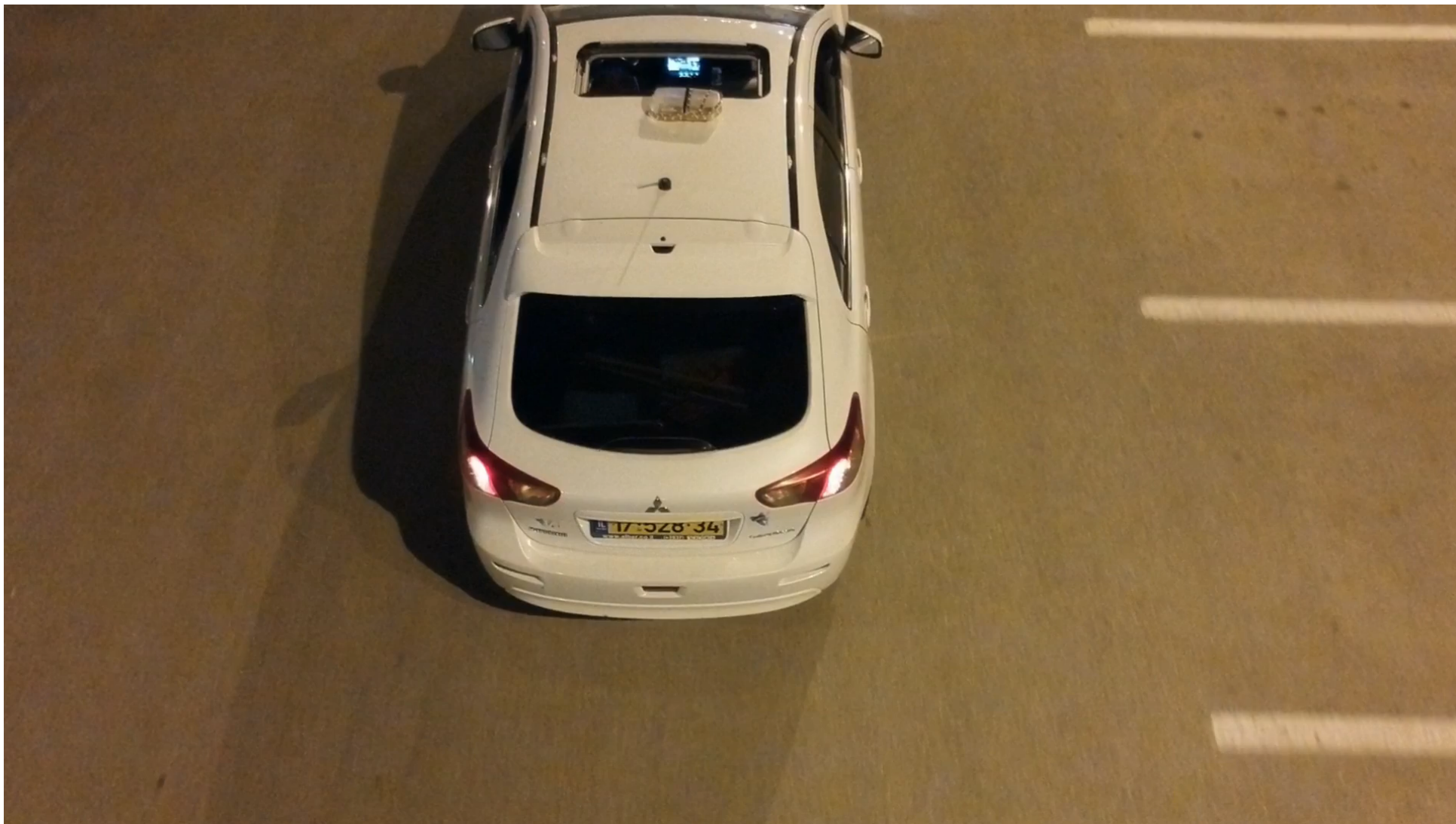




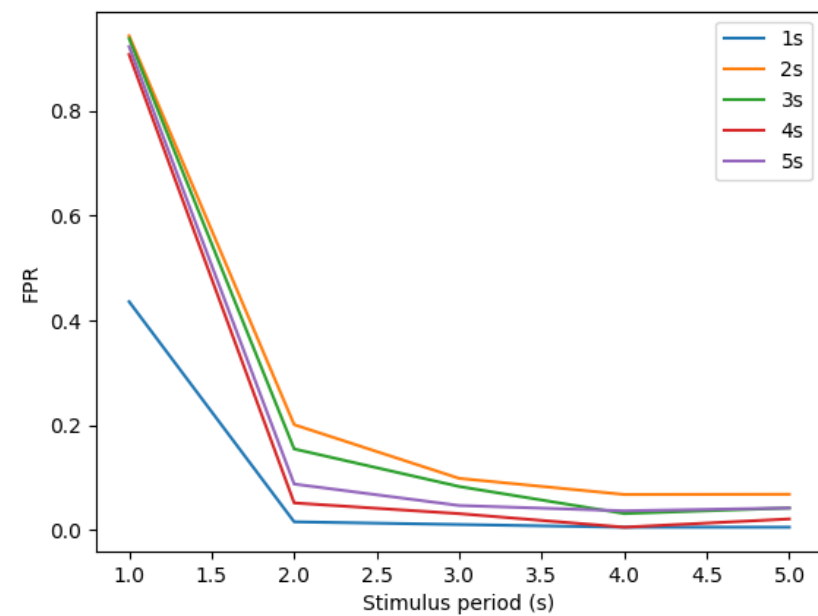
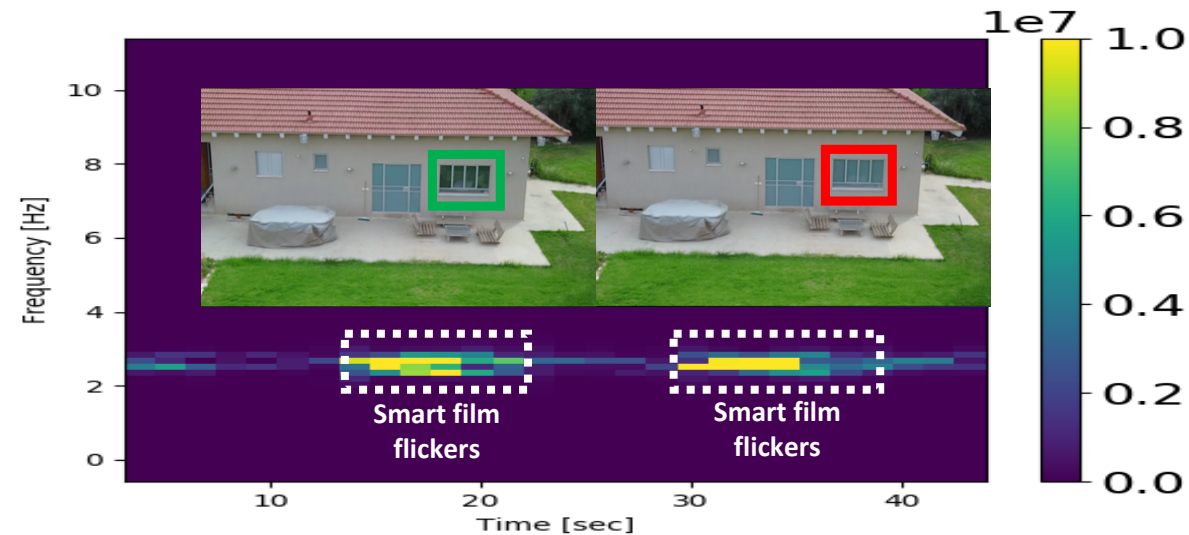
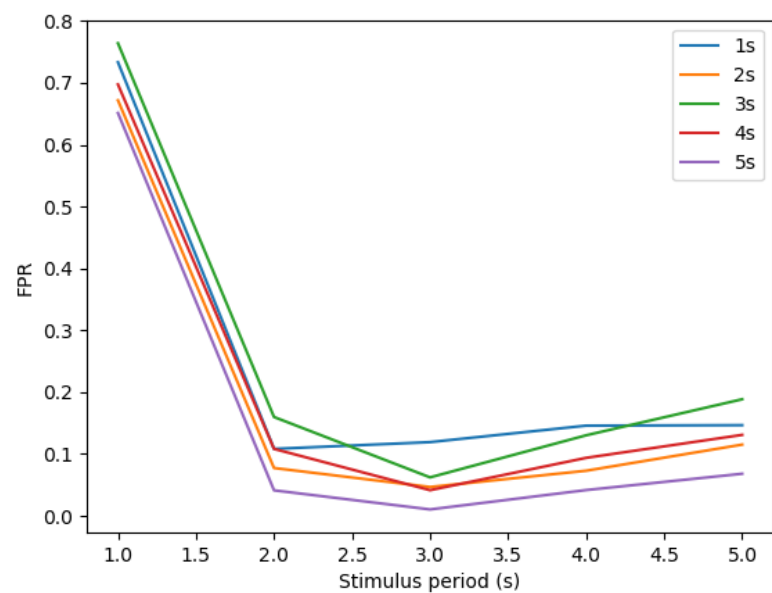
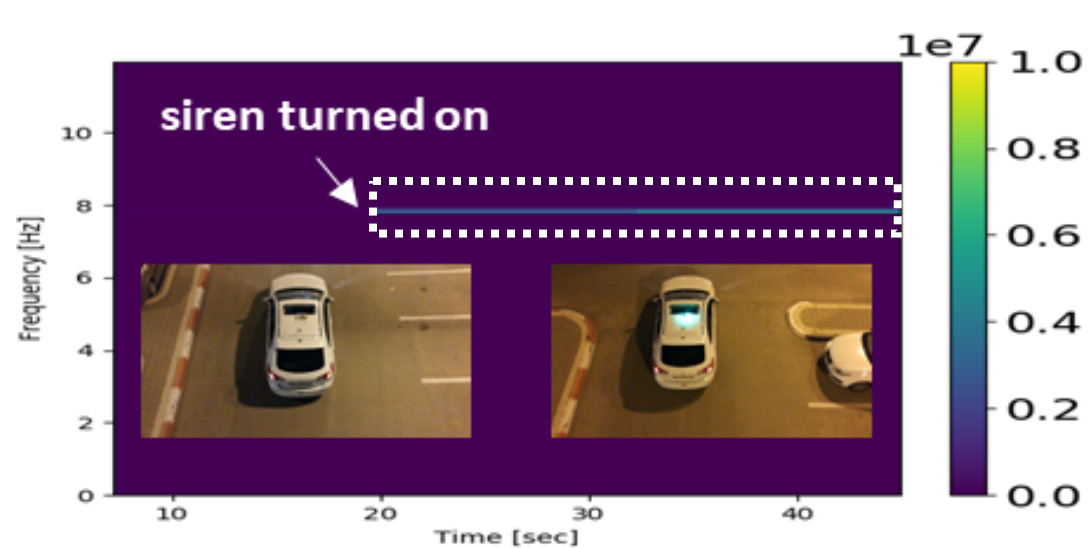
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# Demos



# Results



# Misc

## Additional Information that can be found In the paper:

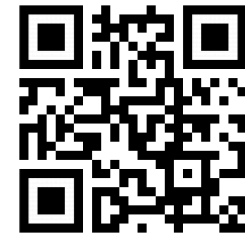
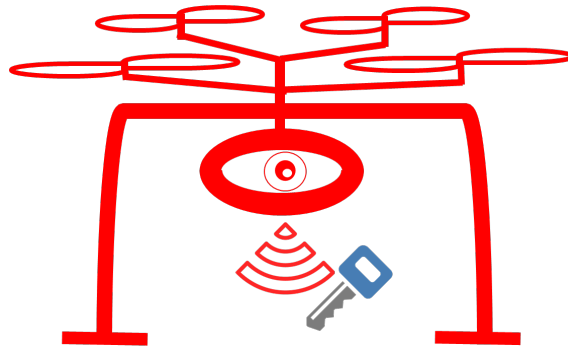
- 1) Locating the spying drone in space
- 2) Countermeasure Methods.
- 3) Analysis of the Impact of Ambient Factors (Wind and Light).
- 4) Other Methods that we considered for hiding the flicker.
- 5) Exact Details of the Experiments.

Others: Preliminary Version of the Paper - Detecting a Privacy Invasion Attack using Time Domain Analysis – [“Game of Drones”, on Arxiv.](#)

# Don't Forget: The P in IoT stands for Privacy.

[@ben\\_nassi](#)

My Twitter



Paper's Website

## Questions???