

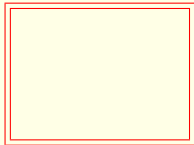
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of the Camtasia video area frame.



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VERIFYING HYPERPROPERTIES with TLA

Leslie Lamport



Fred B. Schneider



[pause] What is a hyperproperty? ©

Hyperproperties

© An ordinary property is a predicate that's true or false of a single execution of a system. ©

For example, the property that every request receives a response. ©

Verifying © that a system satisfies a property © means showing that every execution of the system satisfies the property. ©

Hyperproperties

Ordinary property: True or false of an execution.

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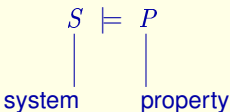
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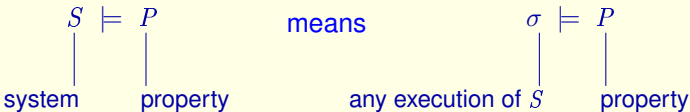
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A hyperproperty is a predicate that's true or false on the set of executions of a system, not just on single executions. ©

Some security conditions are naturally expressed as hyperproperties—for example ©

Observational Determinism or OD. OD assumes that an execution is a © sequence of states, and a state © consists of two parts: © a public state and a secret state. ©

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$(4, "foo")$
| |
public secret

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OD requires that if any two executions © have the same initial public states, then they © always have the same public states. ©

This is an assertion about pairs of executions, not about a single execution. ©

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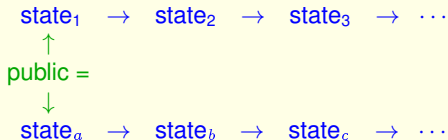
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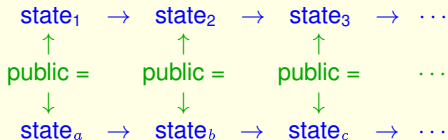
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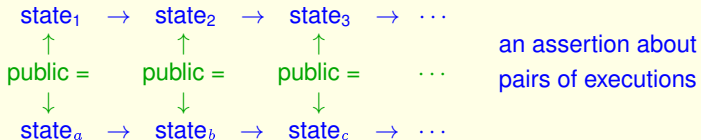
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GNI (Generalized NonInterference)

Another example is GNI (short for Generalized NonInterference). ©

It assumes that an execution is a sequence of public and secret events. ©

It's a way of saying that the public events give you no information about the secret events. ©

For any two possible system executions ©

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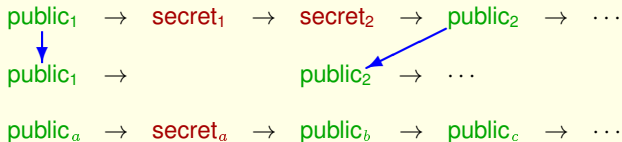
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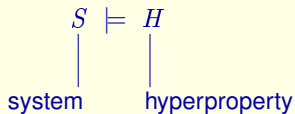
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Verification:

How do we verify C that a system satisfies a hyperproperty? C C

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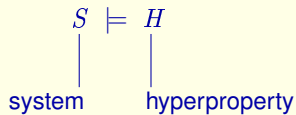
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Verifying Properties

$$S \models P$$

Verifying ordinary properties © has been well-studied. ©

We want to make use of methods and tools developed to solve it. ©

So people have reduced verifying hyperproperties to verifying ordinary properties.
Here's how. © Define two mappings. ©

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Verifying Hyperproperties by Verifying Properties

Two mappings:

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The first maps a system S to another systems $\Omega(S)$. ©

The second maps a hyperproperty H to an ordinary property $H\text{-tilde}$. ©

These mapping are defined so that © system S satisfies hyperproperty H ©

if and only if the system $\Omega(S)$ satisfies the ordinary property $H\text{-tilde}$. ©

Verifying Hyperproperties by Verifying Properties

Two mappings:

$$\begin{array}{ccc} \Omega : S & \rightarrow & \Omega(S) \\ | & & | \\ \text{system} & & \text{system} \end{array}$$

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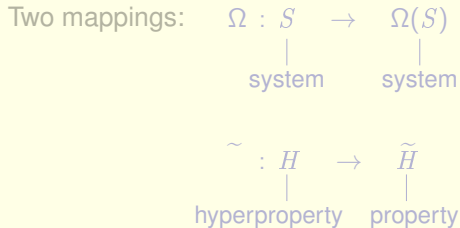
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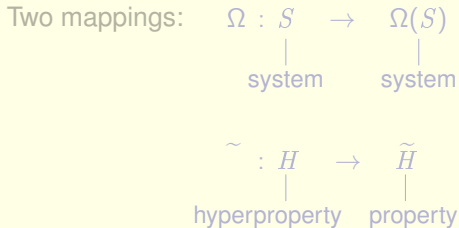
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Verifying Hyperproperties by Verifying Properties



Such that: $S \models H$

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Self-Composition

Verification has been done this way with a method called self-composition ©
where if hyperproperty H is an assertion about n executions ©
then $\Omega(S)$ is a big system that executes n copies of S in lock-step ©
and H tilde is H restated in terms of executions of the individual
processes S in an execution of $\Omega(S)$.

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If H is an assertion about n executions

$$\text{then } \Omega(S) = \underbrace{S \otimes S \dots \otimes S}_{\substack{n \text{ copies} \\ \text{executed in lock-step}}}$$

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If H is an assertion about n executions

then $\Omega(S) = S \otimes S \dots \otimes S$

$\tilde{H} = H$ stated in terms of executions
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Self-Composition

Example: OD

For example, suppose the hyperproperty H is Observational Determinism. ©

Then $\Omega(S)$ consists of two copies of S run in lock step, and ©

H tilde asserts that, if those two copies of S start with equal public states, ©

then they will always have equal public states. ©

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Self-Composition – The Problem

There's a problem with this kind of Self-Composition. ©

It doesn't work for some security hyperproperties, including GNI. ©

GNI says that, for any two behaviors of S © there exists a 3rd behavior of S satisfying a certain condition. ©

With self-composition ©

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With self-composition © these two behaviors © are described by this big system $\Omega(S)$. ©

The 3rd behavior of S © is described by GNI, ©

So GNI-tilde must contain system S , which it can't because GNI-tilde is a property, and how can you put a system in a property?

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Self-Composition – The Problem

GNI: For any two behaviors, there exists a 3rd behavior.

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must contain another copy of system S

public₁ → secret₁ → secret₂ → public₂ → ...

public₁ → secret_a → public₂ → ...

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Self-Composition – Our Solution

Here is our solution ©

Self-Composition – Our Solution

Works for GNI and ...

Here is our solution © It works for some additional security properties, including GNI. ©

TLA (temporal logic of actions)

We use the temporal logic TLA. ©

TLA (temporal logic of actions)

Used by Microsoft, Amazon Web Services, Oracle, ...

TLA has industrial-strength tools and is used by engineers who build large, distributed systems. ©

TLA describes systems, as well as properties, as formulas. ©

System S satisfies property P © means that the formula, S implies P is true. ©

The system obtained by running n copies of S in lock-step is defined as follows. ©

The definition begins with S (of x -sub-1), which is the formula obtained by substituting a new set of variables, x -sub-1, for the variables of S . ©

TLA

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Properties & systems are formulas.

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$S \otimes S \dots \otimes S$ equals

TLA has industrial-strength tools and is used by engineers who build large, distributed systems. ©

TLA describes systems, as well as properties, as formulas. ©

System S satisfies property P © means that the formula, S implies P is true. ©

The system obtained by running n copies of S in lock-step is defined as follows. ©

The definition begins with S (of x -sub-1), which is the formula obtained by substituting a new set of variables, x -sub-1, for the variables of S . ©

TLA

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$S(x_1)$

S with new set x_1 of variables

The definition begins with S (of x -sub-1) which is the formula obtained by substituting a new set of variables, x -sub-1, for the variables of S . ©

Formula S (of x -sub-1) asserts that the values assumed by the variables of x -sub-1 during an execution satisfy the specification of system S . ©

And similarly for S of x -sub-2 through n , all different sets of variables. ©

In TLA conjunction is parallel composition, so this is a system composed of n copies of system S executing in parallel. ©

TLA

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$$S(x_1) \wedge S(x_2) \dots \wedge S(x_n)$$

parallel composition of n copies of S

In TLA conjunction is parallel composition, so this is a system composed of n copies of system S executing in parallel. ©

and K asserts that the copies run in lock-step. I don't have time to explain how K is defined. ©

It's now easy to define define the property asserting that S satisfies GNI. ©

Here are the 2 copies of S that execute in lock-step.

TLA

Properties & systems are formulas.

$$S \models P \quad \equiv \quad \models (S \Rightarrow P)$$

$S \otimes S \dots \otimes S$ equals

$$S(x_1) \wedge S(x_2) \dots \wedge S(x_n) \wedge K(x_1, \dots, x_n)$$

copies run in lock-step

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$$S \models GNI \quad \equiv \quad \models (S(x_1) \wedge S(x_2) \wedge K(x_1, \dots, x_n))$$

2 copies of S run in lock-step

Here are the 2 copies of S that execute in lock-step.

This composite system must satisfy—that is, this formula must imply— \textcircled{C}

that there exists another execution of S

represented by the values of variables x -sub 3 \textcircled{C}

with the right relation among the 3 executions—

that is, the values of the public variables of x -sub 3 equal those of x -sub 1

and the values of its secret variables equal those of x -sub-2. \textcircled{C} \textcircled{C}

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$$S \models GNI \quad \equiv \quad \models (S(x_1) \wedge S(x_2) \wedge K(x_1, \dots, x_n) \\ \Rightarrow \exists x_3 : S(x_3))$$

exists a 3rd execution of S

Here are the 2 copies of S that execute in lock-step.

This composite system must satisfy—that is, this formula must imply—

that there exists another execution of S
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$$S \models GNI \quad \equiv \quad \models (S(x_1) \wedge S(x_2) \wedge K(x_1, \dots, x_n) \\ \Rightarrow \exists x_3 : S(x_3) \wedge L(x_1, x_2, x_3))$$

relation among the 3 executions

Here are the 2 copies of S that execute in lock-step.

This composite system must satisfy—that is, this formula must imply— \textcircled{C}

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It's Not So Easy

Unfortunately, expressing GNI is not this easy. ©

TLA, like most temporal logics, models a system execution as a sequence of **states**. ©

GNI and some other security hyperproperties were originally described in terms of executions as sequences of **events**. © ©

To translate from events to states, we model an event as a change of state.

It's Not So Easy

TLA models executions as sequences of **states**.

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GNI based on executions as sequences of **events**.

public₁ → secret₁ → secret₂ → public₂ → ...

Public **events** must reveal nothing about secret **events**.

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TLA models executions as sequences of **states**.

GNI based on executions as sequences of **events**.

Translate events to states by: $\text{event} = \text{state}_1 \rightarrow \text{state}_2$

Unfortunately, expressing GNI is not this easy. ©

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To translate from events to states, we model an event as a change of state.

It's Not So Easy

For GNI, assume a state is (public state, secret state) .

To translate GNI, we assume a state is a (public-state, secret-state) pair. ©
Like this. ©

A public event © is one that changes the public state. ©

A secret event © is one that changes the secret state. ©

It's Not So Easy

For GNI, assume a state is (public state, secret state).

(4, "foo")
| |
public secret

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A public event (9, "foo")
 | |
 public secret

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A **secret** event (9, "foo")
 | |
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A **secret** event (9, "far")
 | |
 public secret

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For GNI, assume a state is (public state, secret state).

... → public₁ → secret₁ → public₂ → ...

So this sequence of events © becomes this sequence of states. ©

This public event changes the public state. © This secret event changes the secret state. ©

So every event is either a public event or a secret event. ©

And the events are replaced by the state changes. ©

And similarly, this sequence of events © becomes this sequence of states. © ©

It's Not So Easy

For GNI, assume a state is (public state, secret state).

$$\begin{aligned} & \dots \rightarrow \text{public}_1 \rightarrow \text{secret}_1 \rightarrow \text{public}_2 \rightarrow \dots \\ \dots \rightarrow & (p_1, s_1) \rightarrow (p_2, s_1) \rightarrow (p_2, s_2) \rightarrow (p_3, s_2) \rightarrow \dots \end{aligned}$$

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It's Not So Easy

For GNI, assume a state is (public state, secret state).

public₁ secret₁ public₂
... → (p₁, s₁) → (p₂, s₁) → (p₂, s₂) → (p₃, s₂) → ...

So this sequence of events © becomes this sequence of states. ©

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For GNI, assume a state is (public state, secret state).

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$\dots \rightarrow \text{public}_1 \rightarrow \text{secret}_1 \rightarrow \text{secret}_2 \rightarrow \text{public}_2 \rightarrow \dots$

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It's Not So Easy

GNI : If these system executions are run in lock-step

$\dots \rightarrow (p_1, s_1) \rightarrow (p_2, s_1) \rightarrow (p_2, s_2) \rightarrow (p_3, s_2) \rightarrow \dots$

$\dots \rightarrow (p_1, s_1) \rightarrow (p_2, s_1) \rightarrow (p_2, s_2) \rightarrow (p_2, s_3) \rightarrow (p_3, s_3) \rightarrow \dots$

The TLA version of GNI which I showed you before asserts that,
if these two system executions are run in lockstep ©

Then there exists a 3rd system execution ©

whose public states come from the 1st execution ©

and whose secret states come from the 2nd execution. ©

But there's a problem here. ©

This state change changes the public state so it's a public event. ©

It's Not So Easy

GNI: If these system executions are run in lock-step
then there exists a 3rd system execution...

... $\rightarrow (p_1, s_1) \rightarrow (p_2, s_1) \rightarrow (p_2, s_2) \rightarrow (p_3, s_2) \rightarrow \dots$

... $\rightarrow (,) \rightarrow (,) \rightarrow (,) \rightarrow (,) \rightarrow \dots$

... $\rightarrow (p_1, s_1) \rightarrow (p_2, s_1) \rightarrow (p_2, s_2) \rightarrow (p_2, s_3) \rightarrow (p_3, s_3) \rightarrow \dots$

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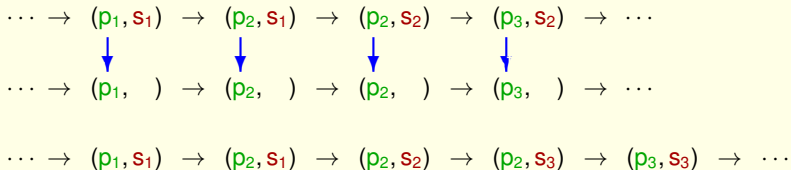
and whose secret states come from the 2nd execution. ©

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... $\rightarrow (p_1, s_1) \rightarrow (p_2, s_1) \rightarrow (p_2, s_2) \rightarrow (p_3, s_2) \rightarrow \dots$

... $\rightarrow (p_1, s_1) \xrightarrow{\text{public}} (p_2, s_1) \rightarrow (p_2, s_2) \rightarrow (p_3, s_3) \rightarrow \dots$

... $\rightarrow (p_1, s_1) \rightarrow (p_2, s_1) \rightarrow (p_2, s_2) \rightarrow (p_2, s_3) \rightarrow (p_3, s_3) \rightarrow \dots$

This state change changes the public state so it's a public event. ©

This state change changes the secret state so it's a secret event. ©

But this state change changes both the secret and public states,
which makes it both a public & secret event. ©

So this isn't a system execution, because GNI assumes that the system allows
state changes that are either public or secret events, but not both. ©

It's Not So Easy

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... $\rightarrow (p_1, s_1) \rightarrow (p_2, s_1) \rightarrow (p_2, s_2) \rightarrow (p_3, s_2) \rightarrow \dots$

... $\rightarrow (p_1, s_1) \xrightarrow{\text{public}} (p_2, s_1) \rightarrow (p_2, s_2) \rightarrow (p_3, s_3) \rightarrow \dots$
secret

... $\rightarrow (p_1, s_1) \rightarrow (p_2, s_1) \rightarrow (p_2, s_2) \rightarrow (p_2, s_3) \rightarrow (p_3, s_3) \rightarrow \dots$

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GNI: If any two system executions are run in lock-step
then ...

This problem is inherent in our TLA definition of GNI. ©

The definition is wrong. ©

It's Not So Easy

~~GNI: If any two system executions are run in lock-step then ...~~

This definition is wrong.

This problem is inherent in our TLA definition of GNI. ©

The definition is wrong. ©

Getting It Right

Instead of being in lock-step,

$\dots \rightarrow (p_1, s_1) \rightarrow (p_2, s_1) \rightarrow (p_2, s_2) \rightarrow (p_3, s_2) \rightarrow \dots$

$\dots \rightarrow (p_1, s_1) \rightarrow (p_2, s_1) \rightarrow (p_2, s_2) \rightarrow (p_2, s_3) \rightarrow (p_3, s_3) \rightarrow \dots$

Instead of having to execute the two copies of the system in lock-step ©

A correct definition of GNI should allow them to be executed like this. ©

GNI assumes these two executions appear the same to public users ©

who just see this. ©

Most formalisms consider these to be different executions because of this extra state. ©

but that means users can tell when secret events occur between public events. ©

TLA considers these two executions to be the same because that extra step leaves the state seen by the user unchanged. ©

Getting It Right

Instead of being in lock-step, the executions should be:

... $\rightarrow (p_1, s_1) \rightarrow (p_2, s_1) \rightarrow (p_2, s_2) \rightarrow \dots$

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Most formalisms consider these to be different executions, implying users can tell when secret events occur between public ones.

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TLA considers them the same because the extra step leaves the visible state unchanged.

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TLA

TLA seems strange because steps that leave the state unchanged can't be required or forbidden by a formula.

TLA at first seems strange to most people because steps that leave the state unchanged can't be required or forbidden by a TLA formula. ©

But that's one reason TLA is simple. ©

This restriction helps ensure that a spec can assert only what it should. ©

For example, a specification of an hour minute clock should not assert that the clock © does not display the temperature © or doesn't display seconds. ©

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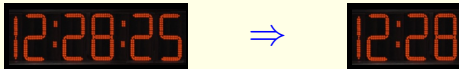
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In the Paper

What's in the paper? ©

I've been doing a lot of hand-waving. The paper contains the details. ©

They're explained with two toy systems that satisfy GNI. ©

There are TLA specifications of these other security hyperproperties. ©

There's a characterization of when a hyperproperty is preserved under refinement. ©

The paper contains toy examples, but TLA is not a toy.

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Relation to machine-checked TLA proof of OD for a real system

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Others have written a machine-checked TLA proof of observational determinism for a real-time message passing system that was later commercialized.

The paper explains the relation of that work to ours. ©

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Model-checked TLA specifications of the examples in the paper. ©

And all about TLA so you can try it yourself.

Thank you.

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